

MLFB-Ordering data

6SL3210-1KE23-8UP1



Client order no.: Order no. : Offer no.: Remarks:

Item no.: Consignment no.: Project:

Rated data	
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Input	
Number of phases	3 AC
Line voltage	380 480 V +10 % -20 %
Line frequency	47 63 Hz
Rated current (LO)	48.20 A
Rated current (HO)	45.20 A
Output	
Noushau of whater	2.40

Output	
Number of phases	3 AC
Rated voltage	400 V
Rated power IEC 400V (LO)	18.50 kW
Rated power NEC 480V (LO)	25.00 hp
Rated power IEC 400V (HO)	15.00 kW
Rated power NEC 480V (HO)	20.00 hp
Rated current (IN)	38.00 A
Rated current (LO)	37.00 A
Rated current (HO)	31.00 A
Max. output current	62.00 A
Pulse frequency	4 kHz
Output frequency for vector control	0 240 Hz
Output frequency for V/f control	0 550 Hz

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Power factor λ	0.70 0.85
Offset factor cos φ	0.95
Efficiency η	0.97
Sound pressure level (1m)	66 dB
Journa pressure level (Till)	OO UD

General tech. specifications

0.50 kW **Power loss** Filter class (integrated) Unfiltered

Ambient conditions

Cooling	Air cooling using an integrated fan
Cooling air requirement	0.018 m³/s (0.636 ft³/s)
Installation altitude	1000 m (3280.84 ft)

Ambient temperature

Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)

Relative humidity

	95 % At 40 °C (104 °F), condensation
Max. operation	and icing not permissible

Closed-loop control techniques

V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No



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			Figure sim	
Mechanical data		Con	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFIBUS DP	
Size	FSC	Co	onnections	
Net weight	4.40 kg (9.70 lb)	Signal cable		
Width	140 mm (5.51 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Height	295 mm (11.61 in)	Line side		
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals	
Inputs / ou	tputs	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)	
Standard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6	
Switching level: 1→0	5 V	DC link (for braking resistor	r)	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
Fail-safe digital inputs		Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)	
Number	1	Line length, max.	15 m (49.21 ft)	
Digital outputs		PE connection	On housing with M4 screw	
Number as relay changeover contact	1	Max. motor cable length	Off flousing with Mr screw	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	150 m (492.13 ft)	
Output (resistive load)	DC 30 V, 0.5 A	Standards		
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Volta Directive 2006/95/EC	
Switching threshold as digital in	put			
0→1	4 V			

Analog outputs

1 → 0

Number 1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1.6 V



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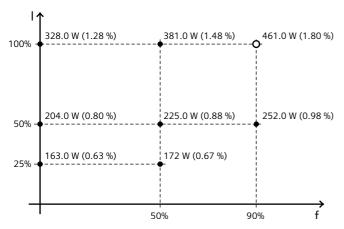
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-64.36 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values

