

MLFB-Ordering data

6SL3210-1KE14-3UB2



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

ltem no. :
Consignment no. :
Project :

Rated data		General tecl	General tech. specifications	
Input		Power factor λ	0.70 0.85	
Number of phases	3 AC	Offset factor cos φ	0.95	
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.97	
Line frequency	47 63 Hz	Sound pressure level (1m)	49 dB	
Rated current (LO)	5.50 A	Power loss	0.06 kW	
Rated current (HO)	4.50 A	Filter class (integrated)	Unfiltered	
Output		Ambian	t conditions	
Number of phases	3 AC	Ambien		
Rated voltage	400 V	Cooling	Air cooling using an integrated fan	
Rated power IEC 400V (LO)	1.50 kW	Cooling singer incoment	0.005	
Rated power NEC 480V (LO)	2.00 hp	Cooling air requirement	0.005 m ³ /s (0.177 ft ³ /s)	
Rated power IEC 400V (HO)	1.10 kW	Installation altitude	1000 m (3280.84 ft)	
Rated power NEC 480V (HO)	1.50 hp	Ambient temperature		
Rated current (IN)	4.30 A	Operation	-10 40 °C (14 104 °F)	
Rated current (LO)	4.10 A	Transport	-40 70 °C (-40 158 °F)	
Rated current (HO)	3.10 A	Storage	-40 70 °C (-40 158 °F)	
Max. output current	6.20 A	Relative humidity		
Pulse frequency	4 kHz	Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Output frequency for vector control	0 240 Hz			
		Closed-loop control techniques		
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parameterizable Yes		
		V/f with flux current control (FC	C) Yes	
Overload capability		V/f ECO linear / square-law	Yes	
Low Overload (LO)		Sensorless vector control	Yes	

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Vector control, with sensor

Encoderless torque control

Torque control, with encoder

No

No

No



Technical data are subject to change! There may be discrepancies between calculated and rating plate values.



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			Figure s	
Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	USS/MODBUS RTU	
Size	FSAA	Connections		
Net weight	1.40 kg (3.09 lb)	Signal cable		
Width	73 mm (2.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 1	
Height	173 mm (6.81 in)	Line side		
Depth	155 mm (6.10 in)	Version	Plug-in screw terminals	
Inputs / outputs		Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 1	
tandard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 1	
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
ail-safe digital inputs		Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 1	
Number	1	Line length, max.	15 m (49.21 ft)	
ligital outputs		PE connection	On housing with M4 screw	
Number as relay changeover contact	1	Max. motor cable length	on housing with we selew	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	100 m (328.08 ft)	
Output (resistive load)	DC 30 V, 0.5 A	S	Standards	
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Vol Directive 2006/95/EC	
witching threshold as digital in	put			
0→1	4 V			

Analog outputs

Number

1→0

1 (Non-isolated output)

1.6 V

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\mathrm{C}$





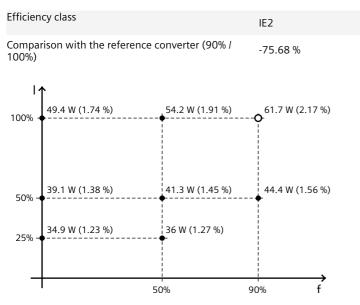
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Figure similar

Converter losses to EN 50598-2*



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values

