

# ATV950U55N4E

Variable speed drive, Altivar Process ATV900, ATV950, 5,5 kW, 400/480 V, w braking unit/ switch, IP55



## Main

|                              |  |
|------------------------------|--|
| Device application           | Industrial application   |
| Device short name            | ATV950   |
| Product destination          | Asynchronous motors<br>Synchronous motors  |
| EMC filter                   | Integrated with 50 m conforming to EN/IEC 61800-3 category C2<br>Integrated with 150 m conforming to EN/IEC 61800-3 category C3  |
| IP degree of protection      | IP55 conforming to IEC 61800-5-1<br>IP55 conforming to IEC 60529   |
| Type of cooling              | Forced convection  |
| Supply frequency             | 50...60 Hz +/- 5 %   |
| Network number of phases     | 3 phases   |
| Motor power kW               | 5.5 kW (normal duty)<br>4 kW (heavy duty)  |
| Motor power hp               | 7.5 hp normal duty<br>5 hp heavy duty  |
| Line current                 | 10.4 A at 380 V (normal duty)<br>9.1 A at 480 V (normal duty)<br>8 A at 380 V (heavy duty)<br>7.2 A at 480 V (heavy duty)  |
| Continuous output current    | 12.7 A at 4 kHz for normal duty<br>9.3 A at 4 kHz for heavy duty   |
| Maximum transient current    | 15.2 A during 60 s (normal duty)<br>14 A during 60 s (heavy duty)  |
| Speed drive output frequency | 0.1...599 Hz   |
| Safety function              | STO (safe torque off) SIL 3  |
| Option module                | Slot A: communication module for Profibus DP V1<br>Slot A: communication module for Profinet<br>Slot A: communication module for DeviceNet<br>Slot A: communication module for EtherCAT<br>Slot A: communication module for CANopen daisy chain RJ45 |

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

Slot A: communication module for CANopen SUB-D 9  
 Slot A: communication module for CANopen screw terminals  
 Slot A/slot B/slot C: digital and analog I/O extension module  
 Slot A/slot B/slot C: output relay extension module  
 Slot B: 5/12 V digital encoder interface module  
 Slot B: analog encoder interface module  
 Slot B: resolver encoder interface module  
 communication module for Ethernet Powerlink

|                             |  |
|-----------------------------|--|
| Range of product            | Altivar Process ATV900                         |
| Product or component type   | Variable speed drive                           |
| Variant                     | With braking chopper<br>With load break switch |
| Mounting mode               | Wall mount                                     |
| Communication port protocol | EtherNet/IP<br>Modbus TCP<br>Modbus serial     |
| [Us] rated supply voltage   | 380...480 V - 15...10 %                        |
| IP degree of protection     | IP55   |

## Complementary

|                       |  |
|-----------------------|--|
| Output voltage        | <= power supply voltage  |
| Frequency resolution  | Display unit: 0.1 Hz<br>Analog input: 0.012/50 Hz  |
| Electrical connection | Control: screw terminal 0.5...1.5 mm <sup>2</sup><br>Line side: screw terminal 4...6 mm <sup>2</sup><br>Motor: screw terminal 4...6 mm <sup>2</sup><br>DC bus: screw terminal 2.5...6 mm <sup>2</sup>  |
| Connector type        | 2 RJ45 for Ethernet IP/Modbus TCP on the control block<br>1 RJ45 for Modbus serial on the control block  |
| Physical interface    | 2-wire RS 485 for Modbus serial  |
| Transmission frame    | RTU for Modbus serial  |
| Transmission rate     | 10/100 Mbit/s for Ethernet IP/Modbus TCP<br>4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial  |
| Exchange mode         | Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP   |
| Data format           | 8 bits, configurable odd, even or no parity for Modbus serial  |
| Type of polarization  | No impedance for Modbus serial   |
| Number of addresses   | 1...247 for Modbus serial  |
| Supply                | External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection<br>Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection<br>Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection |
| Local signalling      | Local diagnostic: 3 LED (mono/dual colour)<br>Embedded communication status: 5 LED (dual colour)<br>Communication module status: 2 LED (dual colour)<br>Presence of voltage: 1 LED (red)   |
| Input compatibility   | DI1...DI8: discrete input level 1 PLC conforming to EN/IEC 61131-2<br>DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68<br>STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2  |
| Discrete input logic  | Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1)<br>Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1)<br>Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1)<br>Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)   |
| Sampling duration     | 2 ms +/- 0.5 ms (DI1...DI8) - discrete input<br>5 ms +/- 1 ms (DI7, DI8) - pulse input<br>1 ms +/- 1 ms (AI1, AI2, AI3) - analog input<br>5 ms +/- 1 ms (AQ1, AQ2) - analog output   |
| Accuracy              | +/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input<br>+/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output   |
| Linearity error       | AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input<br>AQ1, AQ2: +/- 0.2 % for analog output   |
| Refresh time          | Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)   |

|                                     |  |
|-------------------------------------|--|
| Isolation                           | Between power and control terminals  |
| Discrete input number               | 10   |
| Discrete input type                 | DI1...DI8 programmable, 24 V DC ( $\leq 30$ V), impedance: 3.5 kOhm<br>DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC ( $\leq 30$ V)<br>STOA, STOB safe torque off, 24 V DC ( $\leq 30$ V), impedance: $> 2.2$ kOhm   |
| Number of preset speeds             | 16 preset speeds   |
| Discrete output number              | 2  |
| Discrete output type                | Logic output DQ+ 0...1 kHz $\leq 30$ V DC 100 mA<br>Programmable as pulse output DQ+ 0...30 kHz $\leq 30$ V DC 20 mA<br>Logic output DQ- 0...1 kHz $\leq 30$ V DC 100 mA   |
| Analogue input number               | 3  |
| Analogue input type                 | AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits<br>AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits   |
| Analogue output number              | 2  |
| Analogue output type                | Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits<br>Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits   |
| Relay output number                 | 3  |
| Relay output type                   | Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles<br>Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles<br>Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles   |
| Maximum switching current           | Relay output R1 on resistive load, $\cos \phi = 1$ : 3 A at 250 V AC<br>Relay output R1 on resistive load, $\cos \phi = 1$ : 3 A at 30 V DC<br>Relay output R1 on inductive load, $\cos \phi = 0.4$ and L/R = 7 ms: 2 A at 250 V AC<br>Relay output R1 on inductive load, $\cos \phi = 0.4$ and L/R = 7 ms: 2 A at 30 V DC<br>Relay output R2, R3 on resistive load, $\cos \phi = 1$ : 5 A at 250 V AC<br>Relay output R2, R3 on resistive load, $\cos \phi = 1$ : 5 A at 30 V DC<br>Relay output R2, R3 on inductive load, $\cos \phi = 0.4$ and L/R = 7 ms: 2 A at 250 V AC<br>Relay output R2, R3 on inductive load, $\cos \phi = 0.4$ and L/R = 7 ms: 2 A at 30 V DC |
| Minimum switching current           | Relay output R1, R2, R3: 5 mA at 24 V DC   |
| Method of access                    | Slave Modbus TCP   |
| Asynchronous motor control profile  | Constant torque standard<br>Optimized torque mode<br>Variable torque standard  |
| Synchronous motor control profile   | Permanent magnet motor<br>Synchronous reluctance motor   |
| Acceleration and deceleration ramps | Linear adjustable separately from 0.01...9999 s  |
| Motor slip compensation             | Automatic whatever the load<br>Not available in permanent magnet motor law<br>Can be suppressed<br>Adjustable  |
| Switching frequency                 | 2...16 kHz adjustable<br>4...16 kHz with derating factor   |
| Nominal switching frequency         | 4 kHz  |
| Braking to standstill               | By DC injection  |
| Apparent power                      | 7.6 kVA at 480 V (normal duty)<br>6 kVA at 480 V (heavy duty)  |
| Prospective line I <sub>sc</sub>    | 50 kA  |
| Protection type                     | Thermal protection: motor<br>Safe torque off: motor<br>Motor phase break: motor<br>Thermal protection: drive<br>Safe torque off: drive<br>Overheating: drive<br>Overcurrent between output phases and earth: drive<br>Overload of output voltage: drive<br>Short-circuit protection: drive<br>Motor phase break: drive<br>Overvoltages on the DC bus: drive<br>Line supply overvoltage: drive<br>Line supply undervoltage: drive<br>Line supply phase loss: drive<br>Overspeed: drive<br>Break on the control circuit: drive   |
| Width                               | 264 mm   |

|                |         |
|----------------|---------|
| Height         | 678 mm  |
| Depth          | 330 mm  |
| Product weight | 10.7 kg |

## Environment

|                                       |  |
|---------------------------------------|--|
| Insulation resistance                 | > 1 MOhm 500 V DC for 1 minute to earth  |
| Noise level                           | 52 dB conforming to 86/188/EEC   |
| Vibration resistance                  | 1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6<br>1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6  |
| Shock resistance                      | 15 gn for 11 ms conforming to IEC 60068-2-27   |
| Environmental characteristic          | Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3<br>Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3   |
| Pollution degree                      | 2 conforming to EN/IEC 61800-5-1   |
| Relative humidity                     | 5...95 % without condensation conforming to IEC 60068-2-3  |
| Ambient air temperature for operation | -15...40 °C (without derating)<br>40...50 °C (with derating factor)  |
| Standards                             | EN/IEC 61800-3<br>Environment 1 category C2 EN/IEC 61800-3<br>Environment 2 category C3 EN/IEC 61800-3<br>EN/IEC 61800-5-1<br>IEC 61000-3-12<br>IEC 60721-3<br>IEC 61508<br>IEC 13849-1  |
| Operating altitude                    | <= 1000 m without derating<br>1000...4800 m with current derating 1 % per 100 m  |
| Operating position                    | Vertical +/- 10 degree   |
| Product certifications                | TÜV  |
| Marking                               | CE   |
| Maximum THDI                          | <48 % full load conforming to IEC 61000-3-12   |
| Electromagnetic compatibility         | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2<br>Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3<br>Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4<br>1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5<br>Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 |
| Ambient air temperature for storage   | -40...70 °C  |

## Packing Units

|                  |           |
|------------------|-----------|
| Package 1 Weight | 21.000 kg |
| Package 1 Height | 5.400 dm  |
| Package 1 width  | 3.900 dm  |
| Package 1 Length | 8.000 dm  |

## Offer Sustainability

|                            |   |
|----------------------------|---|
| Sustainable offer status   | Green Premium product   |
| REACH Regulation           | <a href="#">REACH Declaration</a>   |
| EU RoHS Directive          | Pro-active compliance (Product out of EU RoHS legal scope)<br><a href="#">EU RoHS Declaration</a>                           |
| Mercury free               | Yes   |
| RoHS exemption information | <a href="#">Yes</a>   |
| China RoHS Regulation      | <a href="#">China RoHS declaration</a>  |
| Environmental Disclosure   | <a href="#">Product Environmental Profile</a>   |
| Circularity Profile        | <a href="#">End of Life Information</a>   |
| WEEE                       | The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins |

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California proposition 65

WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to [www.P65Warnings.ca.gov](http://www.P65Warnings.ca.gov)

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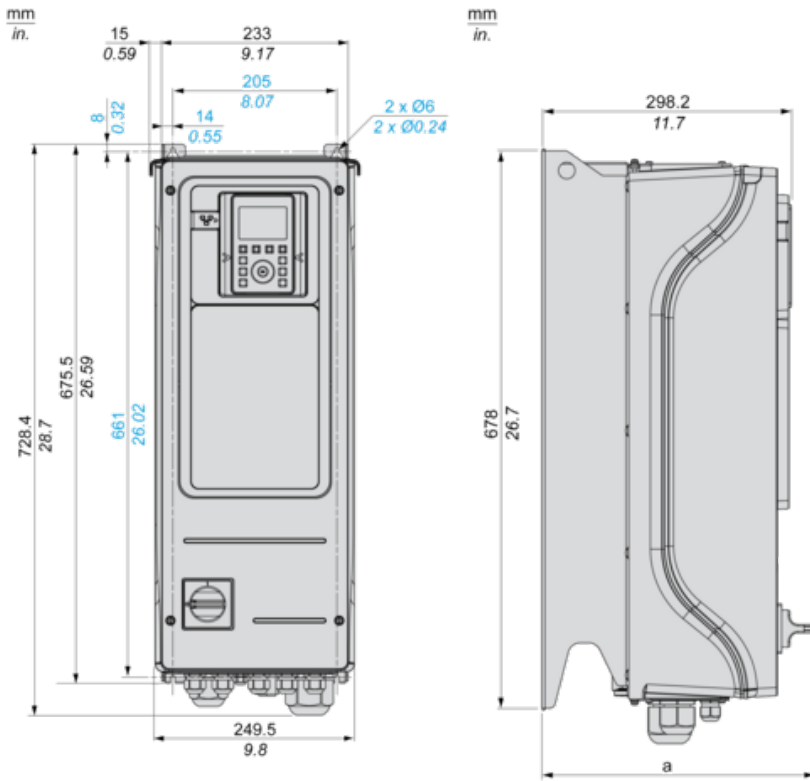
Upgradeability

[Upgraded components available](#) 

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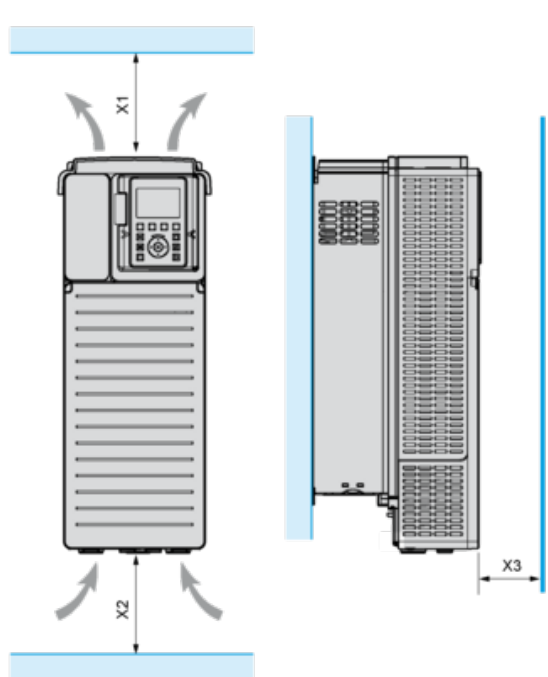
Dimensions

Front and Left View



a = 300 mm (11.8 in.)

Clearances

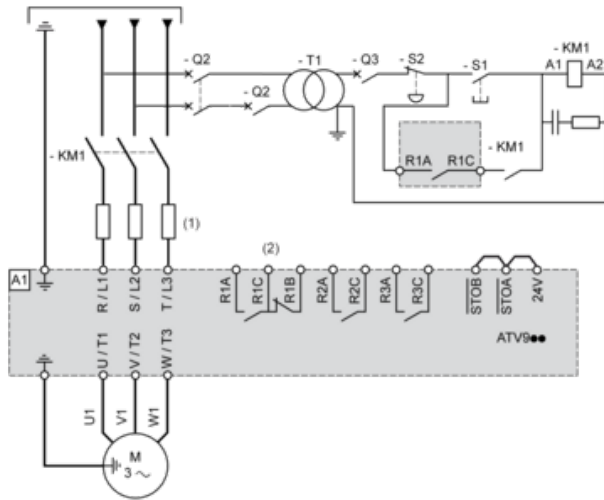


| X1                  | X2                  | X3                 |
|---------------------|---------------------|--------------------|
| ≥ 100 mm (3.94 in.) | ≥ 100 mm (3.94 in.) | ≥ 10 mm (0.39 in.) |

- Mount the device in a vertical position ( $\pm 10^\circ$ ). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

## Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Line Contactor

Q2, Q3 : Circuit breakers

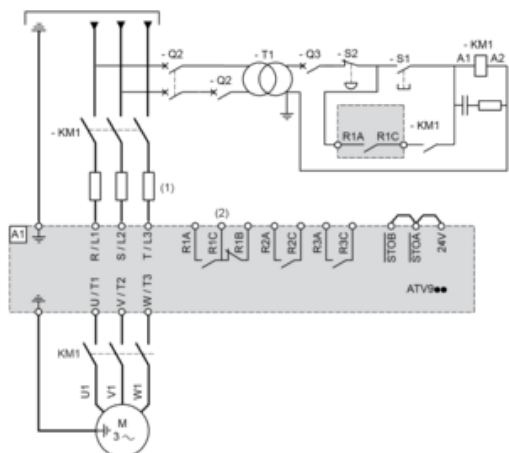
S1, S2 : Pushbuttons

T1 : Transformer for control part



Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



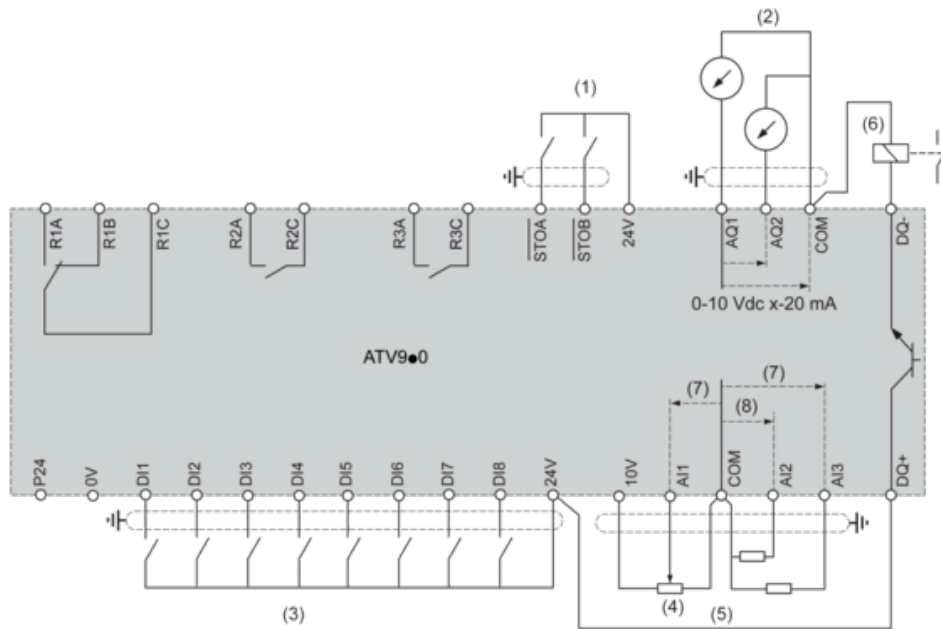
(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

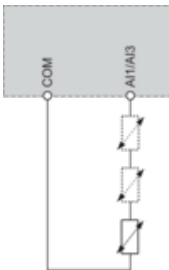
KM1 : Contactor

## Control Block Wiring Diagram



- (1) Safe Torque Off
  - (2) Analog Output
  - (3) Digital Input
  - (4) Reference potentiometer
  - (5) Analog Input
  - (6) Digital Output
  - (7) 0-10 Vdc, x-20 mA
  - (8) 0-10 Vdc, -10 Vdc...+10 Vdc
- R1A, R1B, R1C : Fault relay  
R2A, R2C : Sequence relay  
R3A, R3C : Sequence relay

## Sensor Connection



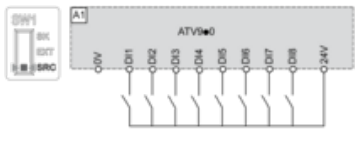
It is possible to connect either 1 or 3 sensors on terminals AI1 or AI3

## Sink / Source Switch Configuration

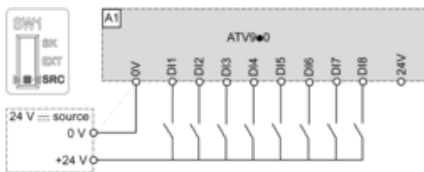
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

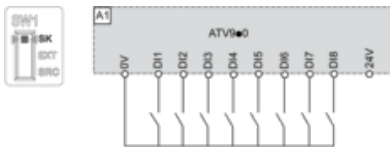
### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



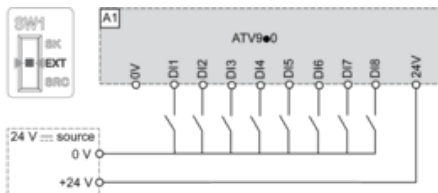
### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



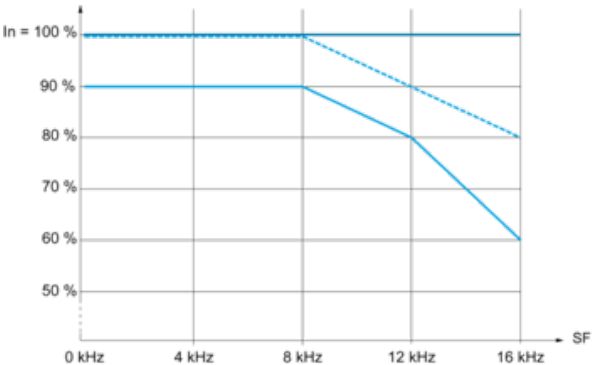
### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



### Switch Set to EXT Position Using an External Power Supply for the DIs



Derating Curves



— 40 °C (104 °F)  
- - - 45 °C (113 °F)  
— 50 °C (122 °F)  
In : Nominal Drive Current  
SF : Switching Frequency